A Multi-channel EEG Data Analysis for Poor Neuro-prognostication in Comatose Patients with Self and Cross-channel Attention Mechanism

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Abstract

*This work is part of the 'Predicting Neurological Recovery from Coma After Cardiac Arrest: The George B. Moody PhysioNet Challenge 2023' to investigate the predictive potential of bipolar electroencephalogram (EEG) recordings towards efficient prediction of poor neurological outcomes. A retrospective design using a hybrid deep learning approach is utilized to optimize an objective function aiming for high specificity, i.e., true positive rate (TPR) with reduced false positives ($\leq$ 0.05). A multi-channel EEG array of 18 bipolar channel pairs from a randomly selected 5-minute segment in an hour is kept. In order to determine the outcome prediction, a combination of a feature encoder with 1-D convolutional layers, learnable position encoding, a context network with attention mechanisms, and finally, a regressor and classifier blocks are used. The feature encoder extricates local temporal and spatial features, while the following position encoding and attention mechanisms attempt to capture global temporal dependencies. Results: The proposed framework by our team, **OUS_IVS**, when validated on the challenge hidden test data, exhibited an unofficial score (not ranked) of **0.416** at 72 hours after the return of spontaneous circulation. The code for this paper is available on GitHub:* https://github.com/HeminQadir/PhysioNet_OUS_IVS.

Keywords— **Deep Learning, PhysioNet, Attention Mechanism, Neuro-prognosis, Cerebral Performance Category, Transformers**

1. Introduction

Assessment of integral neurological outcomes in comatose patients after cardiac arrest is an ongoing scientific challenge to the clinical world. The current prognostication methods on comatose patients with the return of spontaneous circulation primarily rely on subjective visual expert scoring of physiological signals. However, this approach is susceptible to inherent subjectivity, leaving a significant number of patients categorized as ambiguous with uncertain prognoses. Multi-channel EEG streams aid in reducing the subjectivity of prognostic evaluation, and several prognostic indicators are already been identified based on the considered outcome (good/poor prognosis) following cardiac arrest [1–4]. Burst suppression and nonreactive EEG patterns indicate a poor prognosis, but the interpretable quantification of EEG streams is a laborious task that demands advanced clinical and neurophysiological expertise, inhibiting the accessibility of EEG-informed prognostication. Automating EEG interpretation has the potential to improve accessibility and diagnostic accuracy.

In recent years, deep learning (DL)-based attention mechanisms have presented an intriguing avenue for further exploration of the multi-channel integration of the brain [5]. The attention mechanisms enable DL models to focus on relevant information while considering the long-range relationships among different parts of inter and intra-channel signals. The attention mechanism has shown remarkable success in natural language processing to capture long-range dependencies compared to convolutional neural networks (CNNs). In this study, we hypothesize that attention mechanisms can enhance the interpretability and predictive power of multichannel EEG data to classify comatose patients with good or poor neurological outcomes. Specifically, we propose that attention mechanisms can effectively discern both self-attention patterns within individual EEG channels and cross-attention patterns among multiple EEG channels, thus providing critical insights into distinct brain activities underlying the comatose state, leading to improved classification accuracy.

This paper contributes to the George B. Moody PhysioNet Challenge 2023 (formerly the PhysioNet/Computing in Cardiology Challenge) [6]. This challenge invited teams to devise automated methods for predicting neurological outcomes from coma after cardiac arrest using a vast international database comprising $> 57,000$ hours of data collected from 1,020 patients across seven hospitals [7].
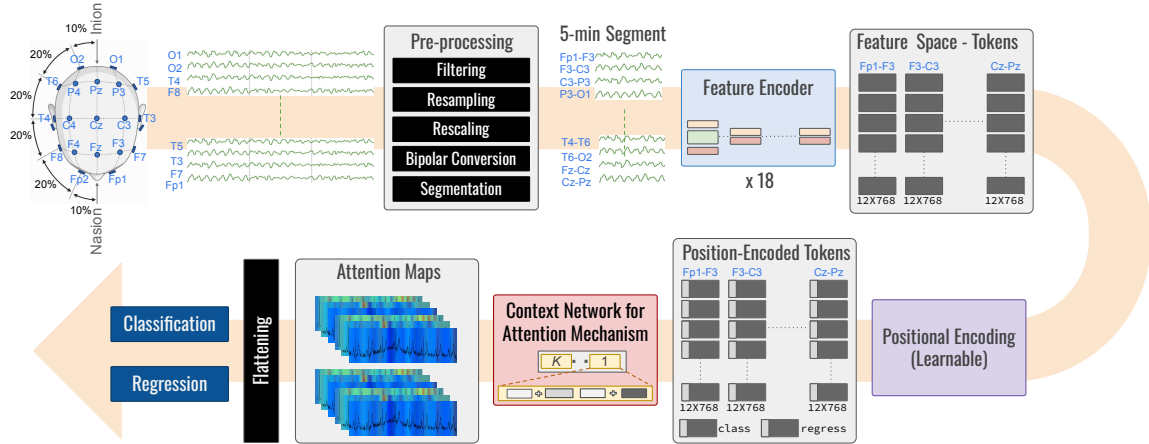
Figure 1. The proposed framework: A raw multi-channel EEG data is fed as initial input to the *Pre-processing* pipeline where the data is filtered, resampled, rescaled, segmented, and converted to bipolar signals. A pre-processed 5-minute segment is fed to *Feature Encoder* which converts each bipolar channel input to a lower-dimensional feature representation called *Tokens* preserving local patterns and spatial relationships. The information about the position of each token in the sequential feature space is encoded by the *Positional Encoding* block. The *Context Network* enables the framework to focus on relevant information while considering the long-range relationships between inter- and intra- channels. The resulting attention maps are flattened and fed to *Classification and Regression* blocks for binary classification and CPC prediction.

2. Materials and Methods

2.1. Pre-processing

The data pre-processing pipeline includes the following sequence of operations: filtering, re-sampling, re-scaling, bipolar conversion, and finally, segmentation of EEG recordings. At the onset, the entire EEG data is filtered using a Butterworth band pass filter with cut-off frequencies of 0.5 Hz and 35 Hz to remove baseline wander and high-frequency noises from the EEG signals. Next, the filtered signals are examined in terms of sampling frequency, and all the EEG recordings are re-sampled to 100 Hz to maintain uniformity with respect to sampling frequencies. The re-sampled signals are then re-scaled using Min-max standardization. Next, re-scaled signals are converted to bipolar representations and finally segmented into 5-minute segments. The bipolar conversion, subtracting EEG signals from adjacent scalp electrodes, is crucial in EEG signal processing. It reduces noise and artifacts, enhances spatial resolution by focusing on localized brain activity, minimizes volume conduction effects, and aids comparisons to baseline states. Valuable in clinical and neuroscience research, it provides a cleaner and more accurate brain activity representation. This data pre-processing pipeline yields a set of 5-minute segments of 18 bipolar channels from every hour of EEG recordings.

2.2. Framework

Figure 1 depicts the proposed framework's design, with further sections explaining each block in detail.

2.2.1. Feature Encoder

In this study, we employ a systematic approach to handle the pre-processed 5-minute segments of 18 bipolar EEG channels. Each bipolar channel segment is passed through its own dedicated feature encoder block, resulting in a total of 18 such blocks. Each feature encoder block consists of a stack of seven 1D CNN layers, as illustrated in Figure 2. The initial layer includes an instance normalization between the 1D convolution and the Gaussian Error Linear Unit (GELU) activation function. The other six layers consist of a 1D convolution followed by a GELU activation function. The total context of the encoder receptive field at 7th layer is 2970 samples with a jump of 2430, corresponding to ~30 seconds at the 100 Hz sample rate. Hence, the feature encoder blocks converted ~30-second fragment to a token. As a result, 12 tokens are generated from each bipolar channel from a 5-minute segment. The output of the feature encoder yields a feature vector with dimensions 12×768 per bipolar channel and a total feature space dimension of 216×768 from the multi-channel EEG array of 18 bipolar channels. This stack of seven 1D CNN layers excels at capturing local patterns and dependencies within the EEG channels with respect to time, effectively reducing the data dimensionality while preserving relevant information. This feature extraction process transforms raw EEG signals into compact representations in the form of tokens that the context network can further process. Tokenization allows the EEG data to be organized into discrete fragments, enabling the attention mechanism to model long-range dependencies and capture complex relationships within inter- and intra- EEG channels.
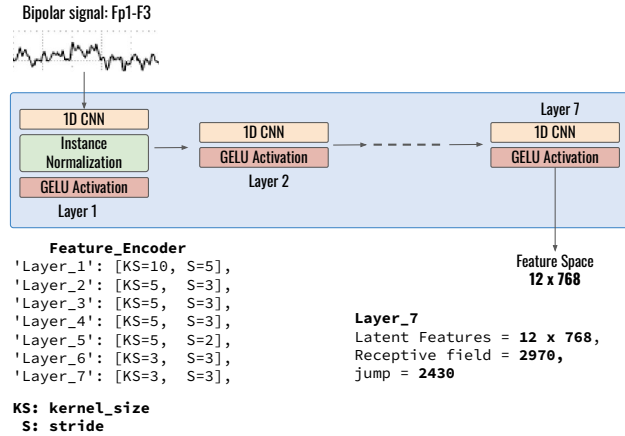
Figure 2. Architecture of the Feature Encoder.

2.2.2. Positional Encoding

Positional encoding adds encoding vectors to the token embeddings, i.e., it encodes information about the position of each token. The significance of positional encoding lies in enabling an attention mechanism (see subsection 2.2.3) to handle sequences of variable length while preserving their order. In the proposed framework, the positional encoding block passes the resultant feature space through learnable positional vectors, which are learned and then appended as addresses to encode the positions of the tokens relative to one another during the training phase. We use a learnable positional encoding scheme over other approaches because it offers flexibility in modeling complex position-dependent relationships, where the patterns in data might not conform to simple sinusoidal functions, and hence, there is a need to capture more nuanced position-based information. Further, if the input sequences have varying lengths, learnable positional encodings can adapt to these variations, ensuring that positional information remains meaningful regardless of sequence length. It is worth mentioning that we prepend learnable $[class]$ and $[regress]$ tokens to the resulting feature space (see Figure 1), leading to the dimension of 218×768. The state value of these two tokens serves as the class and regression representations in the feature space.

2.2.3. Context Network

As shown in Figure 3, the context network of the attention mechanism comprises K attention blocks in succession. Each attention block applies multi-head attention with M heads and a subsequent feed-forward network, both followed by layer normalization. The feature encoder uses convolutional filters with limited receptive fields, with 2970 samples designated for the last layer. This yields the feature encoder suitable for capturing local patterns and short-term dependencies. However, EEG multi-channel data analysis can benefit from global patterns and long-range dependencies across various time steps. We ad-

dress this by proposing a hybrid architecture combining 1D CNNs and attention mechanisms. This hybrid approach aids in modeling and extracting features from EEG data with both short-term and long-term dependencies. Using
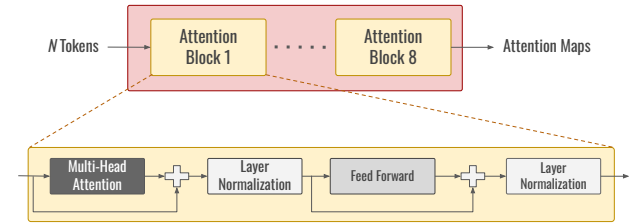

Figure 3. Context Network for Attention Mechanism.

our context network, we aim to capture hierarchical temporal dependencies by combining short-term patterns captured by the feature encoder to form longer-term patterns. Such a design seeks to model the interaction between patterns at different time scales. The resulting feature space contains tokens created from 18 bipolar EEG channels. This token fusion approach facilitates the context network to model long-range dependencies and capture complex relationships within inter- and intra-EEG channels simultaneously without adding complexity to the model design.

2.2.4. Classification and Regression

The context network is followed by two blocks: the classification and regression blocks. Both these blocks consist of a single layer of fully connected neurons. Once the attention maps are obtained, they will be flattened into a vector that these two blocks can handle. The classification block attempts to forecast the neurological outcome, which is a binary decision: "0" for a good outcome or "1" for a poor outcome. In contrast, the regression block aims to predict the Cerebral Performance Category (CPC) value, which is an ordinal scale ranging from 1 to 5 [7].

2.3. Training Details

Attention mechanisms typically require a substantial amount of training data to capture inherent correlations. This is accomplished by adapting a segmentation approach for the selected hour of EEG recording into 5-minute segments. To further enhance training robustness, each iteration is started by randomly selecting an hour of EEG recording of a patient, followed by a segmentation strategy, and then selecting a random 5-minute segment from the corresponding random hour. Using this random selection and 5-minute segmentation techniques, we could generate ∼0.5 million training samples from EEG recordings of 607 patients (See Section 3).

We performed a patient-stratified data split on a given training dataset, resulting in two in-house subsets: an 80% training set and a 20% validation set. The validation set

Table 1. Assessment of our framework along with the challenge score (true positive rate at false positive rate of 0.05)

Time	Challenge Score			Performance Metrics on Test					
(Hours)	Train	Valid	Test	AUROC	AUPRC	ACC	F-Measure	CPC MSE	CPC MAE
12	0.165	0.119	0.149	0.628	0.746	0.703	0.537	3.267	1.692
24	0.325	0.284	0.371	0.758	0.838	0.775	0.724	3.424	1.599
48	0.421	0.507	0.545	0.826	0.902	0.761	0.728	3.671	1.579
72	0.424	0.537	0.416	0.794	0.880	0.761	0.727	3.779	1.602

served as a means for frequently assessing the trained model's performance, and the best model, determined by the highest accuracy, was retained. Adam optimizer is applied to update the model's weights with a batch size of 10 and a learning rate of 0.0001 with 40,000 epochs. For the classification task, we adapted the cross-entropy loss function, tailored to the 'Good' and 'Poor' neurological outcome labels:

$$L_{(\hat{y},y)} = -\frac{1}{N} \sum_{i=1}^{N} [y_i \log(\hat{y}_i) + (1 - y_i) \log(1 - \hat{y}_i)]$$
(1)

where N is the batch size, y_i is the true label ($y_i = 1$ for 'Good' and $y_i = 0$ for 'Poor'), and $\hat{y}_i$ is the predicted outcome for the i-th patient. For the regression task, we utilized the Mean Squared Error (MSE) loss function to predict the CPC values:

$$L_{(MSE)} = \frac{1}{N} \sum_{i=1}^{N} (x_i - \hat{x}_i)^2$$
(2)

where x_i stands for the true CPC value, and $\hat{x}_i$ is the predicted CPC value for the i-th patient. The total loss for the model is the sum of these two losses, encompassing both classification and regression objectives:

$$L_{(total)} = L_{(\hat{y},y)} + L_{(MSE)}$$
(3)

3.   Results

The data under study is provided by the PhysioNet/CinC Challenge 2023 assembled by the International Cardiac Arrest Research Consortium (I-CARE) [7, 8]. The performance of our framework was evaluated officially on the training, validation, and hidden test dataset to yield a challenge score of 0.424, 0.537, and 0.416, respectively for 72 hours. Table 1 details the performance of our algorithm at different time windows and various performance metrics on the official test data.

4.   Discussion and Conclusion

Our initial exploration focused on the last 5-minute segment of the last hour using only 2 bipolar channels with 2 attention blocks each comprising 2 heads. However, this resulted in over-fitting. So, our next approach focused on the random 5-minute segment of the retained random hour, while keeping the same framework design. This improved

our results, indicating the elimination of over-fitting. Finally, we tried to increase the effect of the attention mechanism from 2 to 8 attention blocks, each with 8 heads, resulting in our best performance as detailed in Table 1.

This study has shown that a hybrid approach combining 1D CNNs and attention mechanisms can discern both local and global self- and cross-attention patterns within single and multiple EEG channels to enhance the interpretability and predictive power, leading to efficient binary classification of comatose patients into neurological outcomes.

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